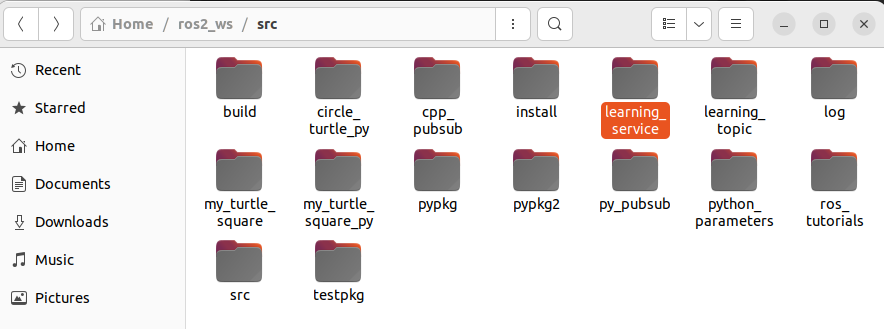
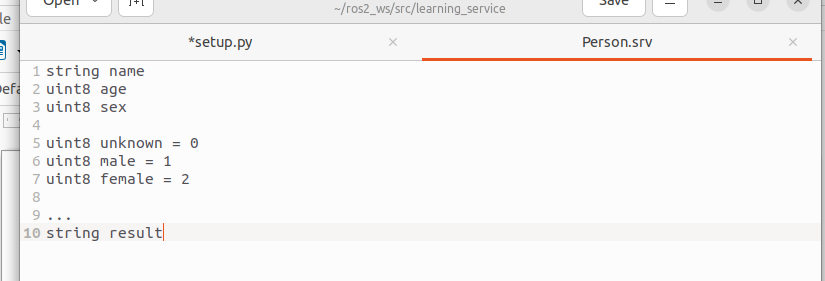
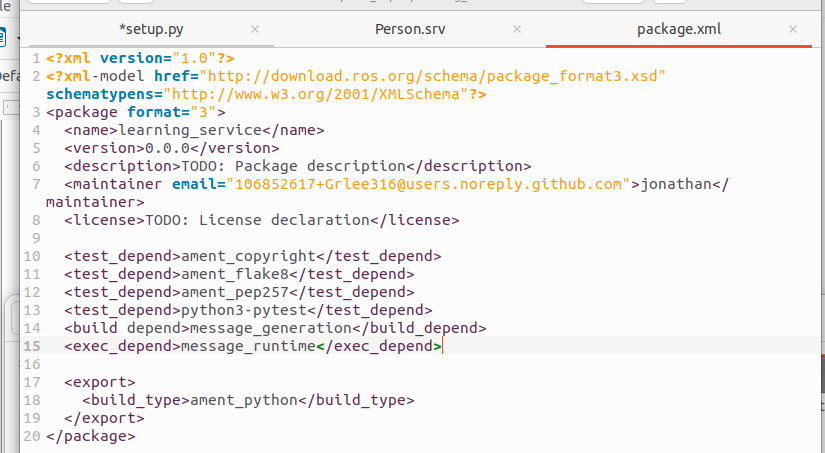
(a) Create a package: learning\_service



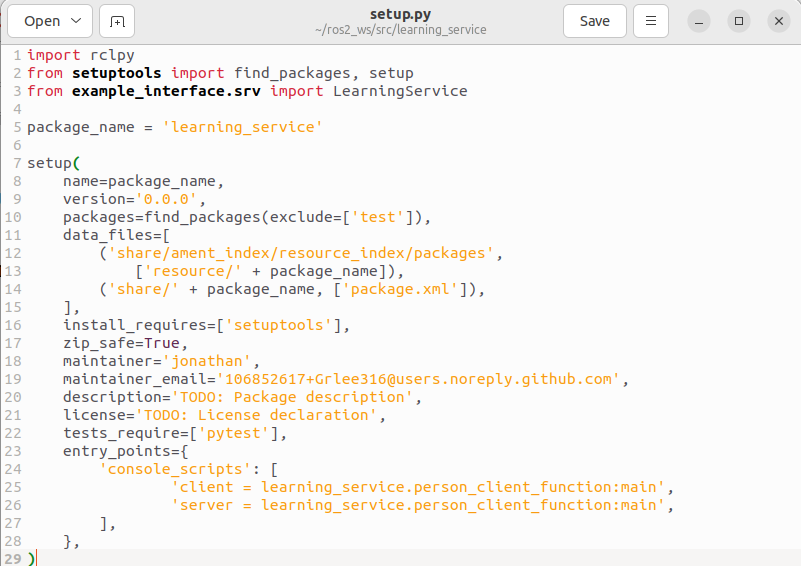
(b) build service file (Person.srv)



(c) Add Dependencies in package.xml



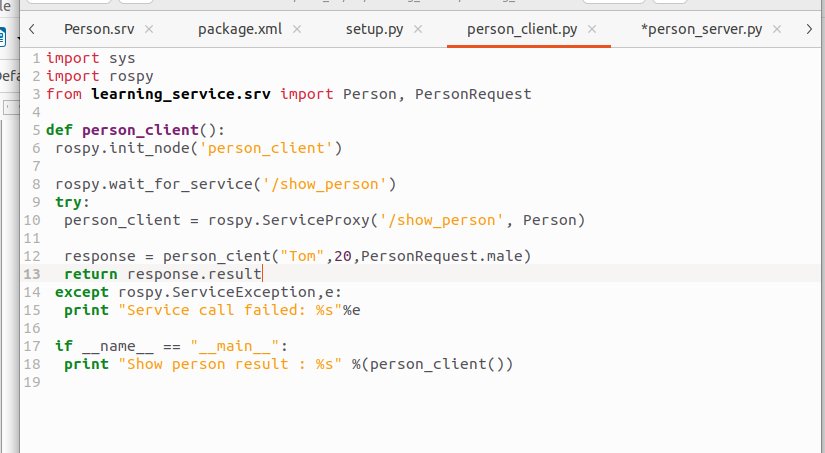
(d) Add compile options in setup.py



(e) catkin\_make Compile

in ROS2, it will be colcon make

(f) Create the Service Client Node Code in Python



(g) Create the Service Server Node Code in Python



(h) Compiling code

(I) Server and Client Compile